

Solver- und Materialmodellentwicklungen bei DYNAmore für die Simulation von Schweißen und Wärmebehandlung



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Simulation of the manufacturing process chain

- For modern processes and materials, the mechanical properties of the finished part highly depend on the fabrication chain
- Tooling has to be compensated for springback and shape distortions which occur in the fabrication chain



Numerical simulations of the complete process chain necessary to predict finished geometry and properties

The individual stages pose very different requirements on the numerical solver





Forming simulation in LS-DYNA

- Different state-of-the-art shell element formulations
- A variety of anisotropic, (visco-)elasto-plastic material formulations
- Forming contacts
- h-adaptivity for improved accuracy and reasonable simulation times
- Implicit (e.g. gravity) and explicit (e.g. closing, drawing) operations
- Trimming functionality







Hot stamping simulation

- Coupled thermo-mechanical simulations
- Thermal contact mechanics
- Among others, tailored material formulation MAT_UHS_STEEL
 - Phase transition of austenite into ferrite, pearlite, bainite and martensite for cooling
 - Thermo-visco-elasto-plastic properties can be defined for individual phases
 - Transformation induced plasticity algorithm
 - Hardness computation
- Tool cooling analysis is also possible

Time = 72.155









Welding simulations – requirements

Realistic description for the heat source applied to the weld seam

Weld seams are usually discretised with solid elements in the pre-processing

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 - Very low heat conduction
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Material should be able to account for the microstructure of the alloy

- Phase changes in heating and cooling
- Transformation induced strains





Agenda

- Modeling Heat Sources in LS-DYNA
 - The Goldak heat source
 - Heat sources with arbitrary shape and prescribed trajectories

- Suitable Material formulations in LS-DYNA
 - *MAT_CWM (*MAT_270)
 - *MAT_THERMAL_CWM (*MAT_T07)
 - *MAT_UHS_STEEL (*MAT_244)

Summary and Outlook





Goldak Double Ellipsoid heat source

double ellipsoidal power density distribution proposed in [Goldak2005]

$$q = \frac{6\sqrt{3}FQ}{\pi\sqrt{\pi}abc} \exp\left(\frac{-3x^2}{a^2}\right) \exp\left(\frac{-3y^2}{b^2}\right) \exp\left(\frac{-3z^2}{c^2}\right)$$

q = weld source power density

(x, y, z) = coordinates of point *p* in weld material

 $F = \begin{cases} F_{f} \text{ if point } p \text{ is in front of beam} \\ F_{r} \text{ if point } p \text{ is behind beam} \end{cases}$

 $c = \begin{cases} c_{\rm f} \text{ if point } p \text{ is in front of beam} \\ c_{\rm r} \text{ if point } p \text{ is behind beam} \end{cases}$



Most widely used for industrial applications

Can be defined in LS-DYNA using keyword *BOUNDARY_THERMAL_WELD





*BOUNDARY_THERMAL_WELD

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|--------|-----|------|-----|-------|------|----|----|------|
| Card 1 | PID | PTYP | NID | NFLAG | X0 | ΥO | ZO | N2ID |
| Card 2 | a | b | cf | cr | LCID | Q | Ff | Fr |
| Opt. | Tx | Τy | Τz | | | | | |

- NID: Node ID giving the location of weld source
- NFLAG: Flag controlling motion of source EQ.1: source moves with node EQ.0: fixed in space
- N2ID: Second node ID for weld beam direction GT.0: beam is aimed from N2ID to NID EQ.-1: beam aiming direction is (Tx, Ty, Tz)





Movement of the heat source 1

- Beam motion (e.g. *BOUNDARY_PRESCRIBED_MOTION_RIGID) allows defining the translation and rotation of the heat source
- For previously deformed or curved structures, the description of the heat source is NOT straight-forward
- Movement of the part has to be compensated for











Movement of the heat source 2

Useful keyword: *CONTACT_GUIDED_CABLE

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|--------|------|-----|-------|--------|--------|--------|---|---|
| Card 1 | NSID | PID | CMULT | WBLCID | CBLCID | TBLCID | | |

It forces beams in PID onto the trajectory defined by nodes in NSID

Possible solution

- Select a trajectory on the weld seam
- Define contact between this trajectory and a beam B1 (N1 and N2)
- Define a second trajectory and a beam B2 (N3 and N4) following it in a prescribed manner
- Welding torch aiming directions from N3 to N1 (*BOUNDARY_THERMAL_WELD)
- Define local coordinate system N1,N2,N3
- Use *BOUNDARY_PRESCRIBED_MOTION_RIGID_LOCAL to move heat source





Movement of the heat source - example

LS-DYNA keyword deck by LS-PrePost







Movement of the heat source - example







Heat sources with arbitrary shape

In some cases the standard Goldak heat source is not suitable
*LOAD_HEAT_GENERATION_OPTION might be useful

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|--------|-----|------|-------|--------|--------|--------|---|---|
| Card 1 | SID | LCID | CMULT | WBLCID | CBLCID | TBLCID | | |

LCID accepts a function id, that returns heat (t, x, y, z)

*DEFINE_FUNCTION

- Define arithmetic expressions involving a combination of independent variables and other functions
- Function name must be unique (heat for heat generation)
- Can be referenced in other functions
- C-type or FORTRAN-style code is possible





*LOAD_HEAT_GENERATION_OPTION







*LOAD_HEAT_GENERATION_OPTION

Example:

Temperature fields for a Goldak and a double cone-shaped heat source







Define heat source for 2D

Can be modeled with flux boundary condition

With *BOUNDARY_FLUX_SEGMENT_SET arbitrarily shaped sources can be defined

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|
| Card 1 | SID | | | | 0. | | | |
| Card 2 | LCID | MLC1 | MLC2 | MLC3 | MLC4 | LOC | NHISV | |
| Card x | HISV1 | HISV2 | HISV3 | HISV4 | HISV5 | HISV6 | HISV7 | HISV8 |

Accepts function ID in LCID, declaration float flux(float x, float y, float z, float vx, float vy, float vz, float tinf, float time)

Application for welding or laser assisted forming processes





*BOUNDARY_FLUX_SET

- Laser assisted sheet forming:
 - the laser heats the material and softens it for forming
 - Energy from the laser is modeled using a flux boundary condition

Deformation

Temperature





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Summary and Outlook





*MAT_CWM / *MAT_270

Elements are initialy "Ghost" or "Silent" until activated at a specific temp.

- Low stiffness
- Negligible thermal expansion
- After activation, material with
 - Temperature dependent mechanical properties
 - Von-Mises plasticity with mixed isotropic/kinematic hardening
 - Thermal expansion
- Anneal at specific temperature







*MAT_CWM / *MAT_270

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|--------|---------|---------|---------|-------|--------|--------|--------|------|
| Card 1 | MID | RO | LCEM | LCPR | LCSY | LCHR | LCAT | BETA |
| Card 2 | TASTART | TAEND | TLSTART | TLEND | EGHOST | PGHOST | AGHOST | |
| Opt. | T2PHASE | T1PHASE | | | | | | |

- Card1 contains properties for activated material
- TASTART and TAEND define range for annealing (linear process)
- TLSTART and TLEND define range for activation
- EGHOST, PGHOST and AGHOST are properties for ghost material
- T2PHASE and T1PHASE define temperature for phase shift

Now available for shell and solid elements





*MAT_THERMAL_CWM / *MAT_T07

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|--------|------|------|---------|---------|---------|-------|--------|--------|
| Card 1 | TMID | TRO | TGRLC | TGRMULT | HDEAD | TDEAD | | |
| Card 2 | LCHC | LCTC | TLSTART | TLEND | TISTART | TIEND | HGHOST | TGHOST |

- Material has birth time TISTART and TIEND
- Before birth, HDEAD and TDEAD are used
- After birth, material is in a "Ghost" state until activated between TLSTART and TLEND
- All input for activated material is temperature dependent
- TGR stands for thermal generation rate



















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The start temperatures for cooling phase transitions can be

- calculated automatically by the material using the chemical composition
- Defined manually using the advanced reaction kinetics input (REACT=1)

By default, same start temperature is used for heating and cooling

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|-------|----|----|----|----|------|---------|--------|--------|
| REACT | FS | PS | BS | MS | MSIG | LCEPS23 | LCEPS4 | LCEPS5 |

Now, advanced reaction kinetics input accepts LCID for FS, PS, BS, MS

First ordinate value is start temperature for cooling

Last ordinate defines start temperature for heating





- Temperature dependent definition for thermal expansion for austenite and the hard phases
- Dilatometer experiments show transformation induced strains as temperature dependent jumps
- Added parameter LCTRE in card 4 on position 8 defining temperature dependent offset between austenite and martensite dilatometer curve







- New features for welding have been implemented
- Can be used by setting flag CWM in card 4 parameter 7 to 1
- Optional CWM card reads

| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|-----|---------|-------|---------|-------|--------|--------|--------|---|
| CWM | TASTART | TAEND | TLSTART | TLEND | EGHOST | PGHOST | AGHOST | |

- Ghost material approach as for *MAT_270
 - Material is inactive at the beginning, but is activated if temperature reaches the activation range from TLSTART to TLEND
 - Properties EGHOST, PGHOST and AGHOST of ghost material should not influence the outcome, but should yield suitable mesh movement within the weld seam
- Annealing is also considered
- Can be combined with *MAT_THERMAL_CWM











Example: Round Robin

Geometry: notched block with 2 weld seams

All materials are initialized in ferrite phase













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Outlook

- A generalization of *MAT_244 will be implemented
 - Suitable for a wider range of materials
 - More phases can be defined
 - Multiple phase transformations
- Special welding contact in currently under development at LSTC
 - Standard sliding contact at the beginning
 - Contact switches to a tied formulation after the weld temperature is reached











